

Defining Redundancy in Fault-Tolerant Systems

(Brief Announcement)

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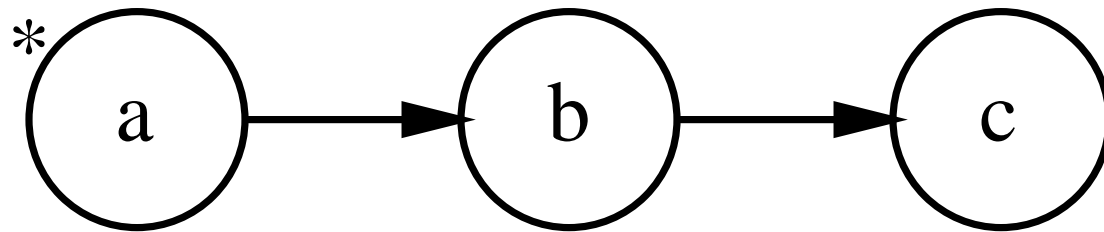
joint work with Hagen Völzer

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(now with SVRC, The University of Queensland, Australia)

Systems

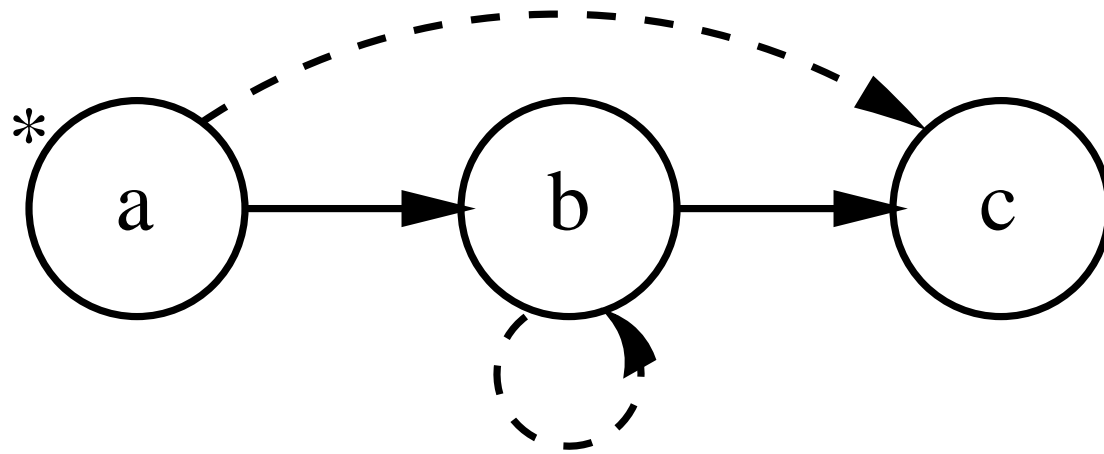
- System $\Sigma = (C, I, T, L)$



- L is a **liveness assumption**.

Faulty Systems

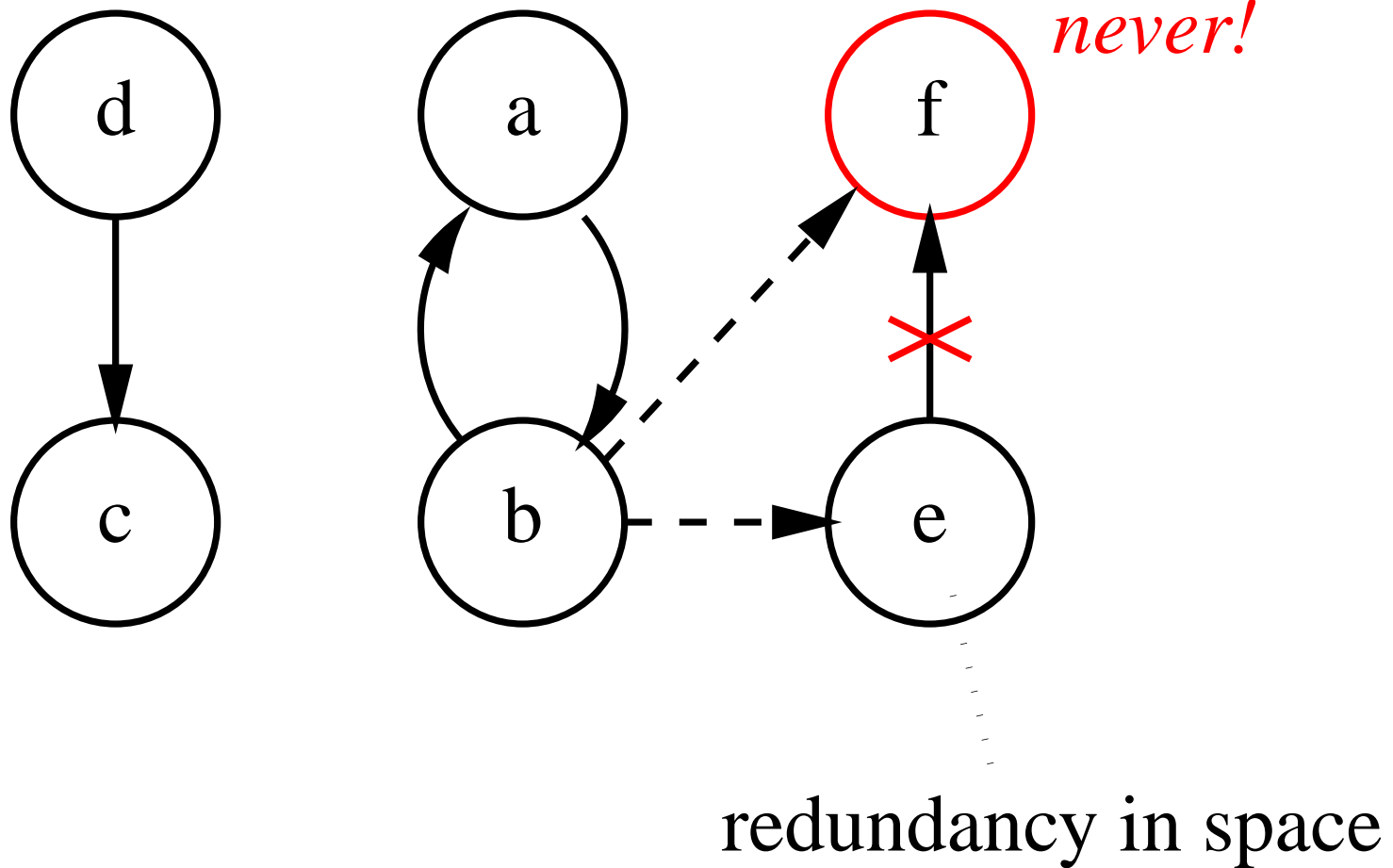
- **Faults** add transitions or weaken liveness assumption.



Fault-Tolerant Systems

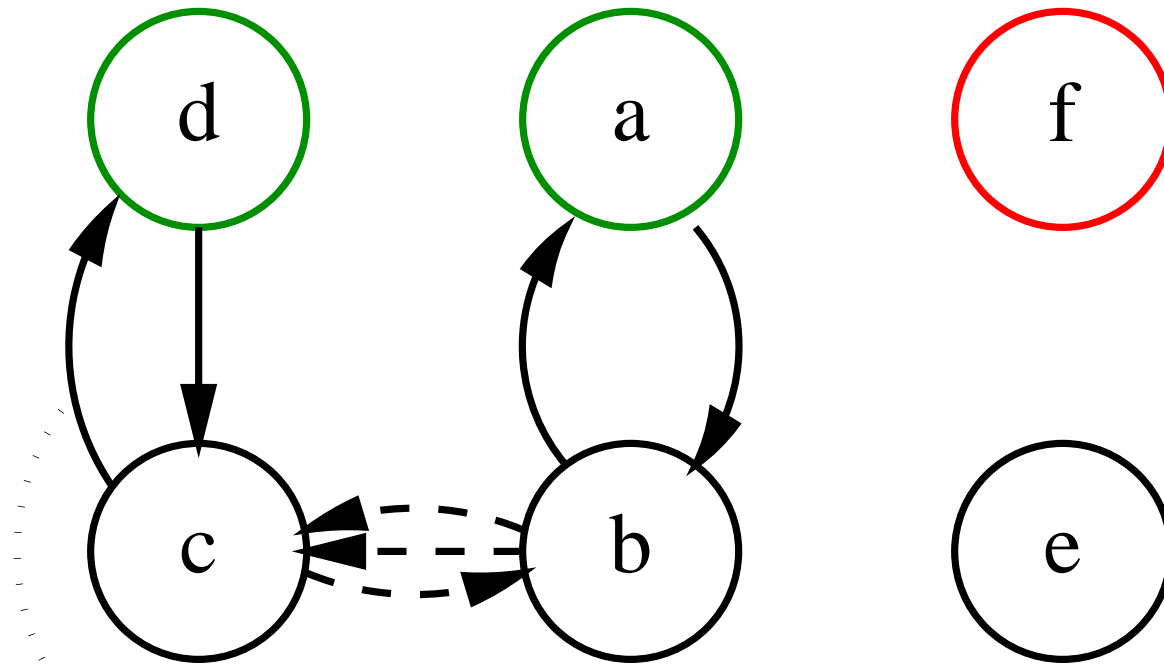
- System Σ **satisfies** a specification *SPEC* in **fault-free environments**.
- Σ **violates** *SPEC* in **faulty environments**.
- What are necessary concepts to **build a system** Σ' from Σ that **satisfies** *SPEC* in **faulty environments**?

Satisfying Safety



Satisfying Liveness

infinitely often!



redundancy in time



Summary of Results

fault-tolerant w.r.t.	necessary
safety	redundancy in space
liveness	redundancy in time + redundancy in space

- One **possible definition** of redundancy.
- Helps explain **fault-tolerance theory** of Arora and Kulkarni [AK98] and **“fault-tolerance compiler”** of Kulkarni and Arora [KA00].

Acknowledgements

- Slides produced using pdfL^AT_EX and Klaus Guntermann's PPower4.

References

- [AK98] Anish Arora and Sandeep S. Kulkarni. Component based design of multitolerant systems. *IEEE Transactions on Software Engineering*, 24(1):63–78, January 1998.
- [KA00] Sandeep S. Kulkarni and Anish Arora. Automating the addition of fault-tolerance. In Mathai Joseph, editor, *Formal Techniques in Real-Time and Fault-Tolerant Systems, 6th International Symposium (FTRTFT 2000) Proceedings*, number 1926 in Lecture Notes in Computer Science, pages 82–93, Pune, India, September 2000. Springer-Verlag.